AMC 600

Programmable Automation Controller with EtherCAT based I/O modules

Data sheet



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1. AMC 600

1.1 About the AMC 600

The AMC 600 is designed as a highly flexible, modular PLC and I/O system covering the special demands of for example wind power plants in terms of reliability, robustness and flexibility.

EtherCAT is used as native communication protocol, as the backplane communication, and as interconnection between multiple AMC 600 racks via electrical or fibre optical connections. Other DEIF EtherCAT I/O modules or third party EtherCAT I/O modules can also be connected.



More information

See www.deif.com/documentation/amc-600/ for the AMC 600 documentation.

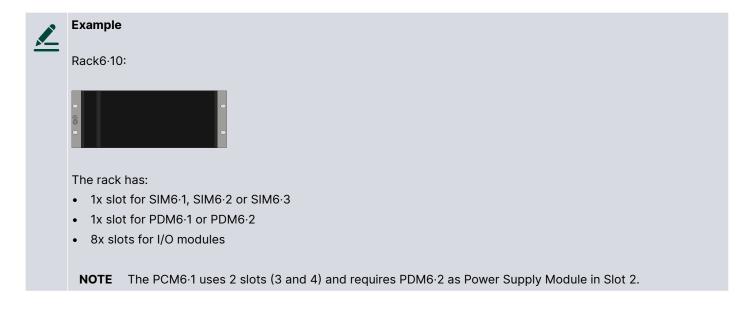
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2. Technical specifications

2.1 System specifications

Rack sizes

| Rack | Slots | Ground plate dimensions HxDxW (mm) | Weight (g) | Rack |
|----------|-------|---------------------------------------|------------|--|
| Rack6·4 | 4 | 122.0 x 113.9 x 182.4 mm | 715 | |
| Rack6·6 | 6 | 122.0 x 113.9 x 233.2 mm | 870 | * |
| Rack6·8 | 8 | 122.0 x 113.9 x 284.4 mm | 1020 | - 8 - |
| Rack6·10 | 10 | 122.0 x 113.9 x 334.8 mm | 1175 | |
| Rack6·12 | 12 | 122.0 x 113.9 x 385.6 mm | 1335 | © 00 00 00 00 00 00 00 00 00 00 00 00 00 |
| Rack6·14 | 14 | 122.0 x 113.9 x 436.4 mm | 1500 | |



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Environment

| Category | Specification | Standard |
|-----------------------|---|--------------------------------|
| Operating temperature | -40 to 70 °C | |
| Storage temperature | -40 to 85 °C | IEC 60068-2-1 IEC 60068-2-2 |
| Reference temperaure | 15 to 30 °C | |
| Altitude | Up-to 4000 m without de-rating (for deployment above 4000 m, contact Product Management). | |
| Climate | All modules are conformal coated, hence protected against moisture, mold, dust, corrosion and other environmental stresses. | IEC 60068-2-30 |
| | 55 °C at 97 % relative humidity, condensing | test Db |
| | Dry heat test | IEC 60068-2-2 |
| | Cold test | IEC 60068-2-1 |

Tests

| Category | Specificati | Specification | | |
|--|---|--|-------------------------------|--|
| Performance test and performance check | Criteria/sta | Criteria/standard: All inputs, outputs and interfaces are functional. | | |
| Radiated E-field emission | 230 to 11 to 3 G1 to 3 G3 to 6 G | 230 to 1,000 MHz: 57 dB (μV/m) Qp 10 m 1 to 3 GHz: 76 dB (μV/m) Q peak 3 m 1 to 3 GHz: 56 dB (μV/m) average 3 m | | |
| Conducted emission | | | IEC 61000-6-4 IEC 60255-26 | |
| Electrical fast transients test (EFT) | Criteria B | Levels extended to: DC-power port: ±4 kV Functional Earth port: ±4 kV Signal input and output ports: ±2 kV Communication ports: ±2 kV Repetition frequencies: 5 KHz and 100 KHz Duration each polarity: 1 min. | EN 61000-4-4 EN 61000-6-2 | |
| RF E-Field immunity | Criteria: A | 80 to 2,000 MHz: 12 V/m 2 to 3 GHz: 10 V/m | EN 61000-4-3 EN 61000-6-2 | |
| Electrostatic discharge (ESD) | Criteria: B | Level extended to: Contact 6 kV | EN 61000-4-2 EN 61000-6-2 | |
| Slow transients test, surge | Criteria: B | Levels extended to: Digital inputs: ±1 kVp DM and ±2 kVp CM Digital outputs: ±1 kVp DM and ±2 kVp CM Analogue inputs: ±3 kVp DM and ±3 kVp CM Analogue outputs: ±1 kVp DM and ±2 kVp CM Temperature inputs: ±3 kVp DM and ±3 kVp CM Main power supply: ±3 kVp DM and ±3 kVp CM Dig output power supply: ±3 kVp DM and ±3 kVp CM RS-422, RS-485, Profibus DP, CAN, Ethernet, SSI: ±2 kVp CM | EN 61000-4-5 EN 61000-6-2 | |

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| Category | Specification Standard | | |
|---|---|--|------------------------------|
| RF common mode conducted test | Criteria: A | 0.15 to 80 MHz: 12 VRMS | EN 61000-4-6 EN 61000-6-2 |
| Power frequency H-field (magnetic) immunity | Criteria: A | Field: 30 A/m | EN 61000-4-8 EN 61000-6-2 |
| | Operation | 3 to 13.2 Hz 2.85 mm peak-peak 13.2 to 100 Hz 1 <i>g</i> | DNV-GL test A |
| | al | 3 to 15 Hz 5 mm peak-peak 15 to 50 Hz 2.3 <i>g</i> | DNV-GL test C |
| Vibration Test | Response | 10 to 58.1 Hz 0.15 mm peak-peak 58.1 to 150 Hz 1 <i>g</i> | IEC 60255-21-1 class 2 |
| | Endurance | 10 to 150 Hz 2 g | IEC 60255-21-1 class 2 |
| | Seismic | 3 to 8.15 Hz 15 mm peak-peak 8.15 to 35 Hz 2 <i>g</i> | IEC 60255-21-3 class 2 |
| Shock (Base mounted) | 10 g, 11 ms, | IEC 60255-21-2 Response class 2 | |
| | 30 g, 11 ms | IEC 60255-21-2 Endurance class 2 | |
| | 50 g, 11 ms | IEC 60068-2-27 | |
| | Tested with 3 impacts in each direction in all 3 axes, a total of 18 impacts per test | | |
| Bump | 25 g, 16 ms | , half sine | IEC 60255-21-2 class 2 |
| | 1,000 bumps in each direction, 2 directions in each axis, a total of 6,000 bumps | | |

NOTE g = gravitational force (g-force).

Safety and protection

| Category | Specification | Standard |
|------------|--|-----------------------|
| Safety | Installation (over-voltage) category III, 600 V, pollution degree 2 | EN 61010-1 |
| Protection | IP30 | IEC/EN 60529/A1/A2 |
| Materials | Aluminium case and cover plates (all plastic parts are self-extinguishing) | UL94 (V1) |

Approvals

These approvals apply to the controller rack (with all the modules properly installed).

| Standards |
|--|
| CE |
| UKCA |
| UL/ULC Listed to UL6200:2019 1st edition |
| LR approval |
| DNV approval (scheduled approval date: 2024) |
| Others available on request |

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2.2 Computer modules

2.2.1 PCM6·1 computer module specifications

The PCM6·1 module offers a powerful dual core 1.2 GHz CPU, well suited for demanding C/C++ and CODESYS applications.

| Computer module | | |
|------------------------|----------------------------------|--|
| | Power supply | From backplane |
| PCM6·1 | Backplane interfaces | 1 x EtherCAT OUT (Port 1) – LVDS 1 x EtherCAT OUT (Port 2) – LVDS |
| 1 13 14 Out 3 15 | Digital input (In) | High: 13 to 30 V Low: -30 to +5 V with reference to common Load: Typically, 6 mA (Vin > 7 V) Isolation: Optically isolated from other potentials, 500 V DC |
| 4 | Digital output (Out) | Solid State Relay with external watchdog, 24 V, maximum 1 A resistive |
| 8 20 | Interface, Ethernet | 2 x Ethernet (Eth1 and Eth2): 1000BASE-T, 8P8C ("RJ45"), shielded Cat 5e, >0.76 μm gold plating |
| 9 10 21 22 22 23 | Interface, CAN | 2 x CAN (CAN 1, CAN 2): ISO 11898, shielded twisted copper cable, 50 to 1,000 kbit/s, software controllable 120 Ω termination resistor |
| 11 12 23 24 USB device | Interface, UART | 2 x RS-422/485 (COM1, COM2) : ANSI/TIA/EIA-422-B and TIA/ EIA-485, shielded twisted copper cable 4.8 to 921.6 kbit/s (full duplex), software controllable 120 Ω termination resistor and 500 Ω bias resistor |
| | Processor | 1.2 GHz dual-core industrial grade ARM Cortex-A7 32 bit CPU (ARMv7) with ECC protected cache |
| | Operating system | DEIF OS, based on real-time embedded Linux® Fail-safe remote SW update Power fail-safe, self-monitoring and error-correcting file system (EXT-4) |
| | PLC run-time | CODESYS V3 runtime : CODESYS V3 SP15 or later |
| | Programming | ANSI C/C++ via PCM6·1 SDK and IEC 61131-3 via CODESYS V3 UL/ULC : Make sure Functional testing is part of the end application. |
| | Protocols | See section Supported software features |
| | Memory | 1 GB DDR3 RAM 64 bit ECC protected Industrial grade |
| | Internal storage | Non-volatile data storage: 4 GB industrial grade flash (pseudo SLC mode) |
| | Real-Time Clock (RTC) battery | Real-time clock with replaceable coin-cell battery (replacement recommended every 5 years). CR2430 3V battery, rated for operation at -40 to 85 °C (-40 to 185 °F). This is not a standard CR2430 battery. The CR2430 battery is an available accessory. Contact DEIF for ordering. |
| | USB host | USB 3.0, Mass Storage Class |
| | USB device | USB 2.0, console on virtual COM port, 115.2 kbit/s (D:8,S:1,P:N,F:N) |
| | Weight | 292 g |
| | Power consumption | Max 16.6 W, hereof 5.6 W reserved for USB3.0 host |

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| Computer module | | |
|---------------------------------------|--|--|
| Connector, grip (included by default) | 2 x 2 terminals: 1790483 2 x 6 terminals: 1790522 2 x 4 terminals: 1790506 | |
| Connector, screw | 2 x 2 terminals: 1790292 2 x 6 terminals: 1790331 2 x 4 terminals: 1790315 | |

LED specifications

| Run LED | | Description |
|--------------------|---|-------------------|
| OFF | • | Initialisation. |
| Green blinking | | Pre-operational. |
| Single green blink | | Safe-operational. |
| Green | • | Operational. |
| Green flickering | | Boot loader. |

| Status LED | | Description |
|--------------------|----|---|
| OFF | • | Off. |
| Red | • | Booting. |
| Red flickering | * | Push the reset button to reset PCM6·1. The module resets in rescue mode. Push and hold the reset button to perform a factory reset. |
| Orange flickering | | Factory reset in progress. |
| Orange | • | Initialisation. |
| Orange blinking | | Rescue mode. |
| Green flickering | | Updating with an update file (.dupdate). |
| Single green blink | | Application mode is not enabled. |
| Green blinking | -> | Initialisation. |
| Green | • | In operation. |

| In LED | | Description |
|--------|---|------------------------------------|
| OFF | • | The digital input is not activate. |
| Green | • | The digital input is activate. |

| Out LED | | Description |
|---------|---|-------------------------------------|
| OFF | • | The digital output is not activate. |
| Green | • | The digital output is activate. |

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Ethernet

The two independent Ethernet ports Eth0 and Eth1 are connected directly to the CPU module. They are configured via the System web page. The use case is, for example, as a gateway between upper plant-wide network segments and local network segments. Both Ethernet ports have broadcast storm filters enabled. These protect the real-time capabilities of the CPU.



More information

See **Communication protocols** in the **Supported software features** section for details about the supported Ethernet protocols, for example Modbus TCP, OPC UA, and PROFINET.

CAN

The two independent CAN ports provide CAN (layer II) support. CANopen Master/Slave communication is done using the CODESYS protocol stacks. The ports are configured using the CODESYS applications. The applications also provide the CAN layer II and CANopen Master/Slave protocol stacks. Enable the termination resistors using the software, mapped to the Linux device interface.

UART

The two UART serial ports can be configured as RS-422 or RS-485. Enable the termination and bias resistors using the software, mapped to the Linux device interface.

USB host

The host supports the connection of USB 3.0 mass storage devices. Use the Linux operating system to add support for other USB devices.

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2.2.2 PCM6·2 computer module specifications

Contact DEIF for availability

NOTE Order this module as an iE 650 PLC.

The PCM6·2 module comes with a powerful 1.6 GHz quad-core (64 bit) CPU, well suited for demanding C/C++ and CODESYS applications. Use the network functions for energy and power applications, for example, wind turbines, power parks, hybrid solutions, and battery storage.

The module has a 1 Gbps TSN network interface port for power management networks that are plant-wide and real-time. The module also features a managed 10/100 Mbps switch with 3 ports for local networks.

The DisplayPort connector allows you to connect standard LED/LCD monitors. CAN/CANopen and RS-422/485 connections are available as on-module interfaces using the common snap-locked (or screw-locked) connector.

| Computer module | | |
|--|-------------------------|--|
| | Power supply | From backplane using PDM6·1 module or PDM6·2 module |
| PCM6-2 | Backplane interfaces | 1 x EtherCAT OUT (Port 1) – LVDS 1 x EtherCAT OUT (Port 2) – LVDS |
| Status 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | Digital input (In) | 1 x DI 24 V DC High: 13 to 30 V Low: -30 to +5 V with reference to common Load: Typically 6 mA (Vin > 7 V) Isolation: Optically isolated from other potentials, 500 V DC |
| 9 10 21 22 USB host 11 12 23 24 | Digital output (Out) | $1 \times DO 24 \ V \ DC$ Solid State Relay with external watchdog, 24 V, maximum 1 A resistive |
| Eth2 | Ethernet | 1 x Ethernet with TSN support (Eth0): 100/1000BASE-T, 8P8C ("RJ45"), shielded Cat5e, gold plating 3 x Ethernet, managed switches (Eth1, Eth2, Eth3): 10/100BASE-T, 8P8C ("RJ45"), shielded Cat5e, gold plating |
| | CAN | 2 x CAN (CAN 1, CAN 2): ISO 11898, shielded twisted copper cable, 50 to 1,000 kbit/s, software controllable 120 Ω termination resistor |
| | UART | 2 x RS-422/485 (COM1, COM2): ANSI/TIA/EIA-422-B and TIA/ EIA-485, shielded twisted copper cable, 4.8 to 921.6 kbit/s (full duplex), software controllable 120 Ω termination resistor and 500 Ω bias resistor |
| | Display port | 1 x DisplayPort (DP) v1.3 1080 p (full-size connector) |
| | USB host | 1 x USB 3.0 (Type-A connector), mass storage class power, delivery up to 4.5 \mbox{W} |
| | LED | RUN: Green, EtherCAT in operation STATUS: Red/Blue/Green, software controllable |
| | Pin-hole switch | Factory reset or provisioning of module (software configurable) |
| | Processor | 1.6 GHz quad-core industrial grade ARMv8 64 bit CPU with ECC protected cache |
| | Memory | 4 GB LPDDR4 with inline Error Code Correction (ECC) |

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| Computer module | |
|---------------------------------------|--|
| Internal storage | 32 GB 3D TLC NAND flash running in pseudo SLC mode. ~8 GB available for user application data |
| Persistent storage | 256 kB FRAM |
| Expandable storage | MicroSD slot: High speed (max. 25 MB/s). The MicroSD slot is accessible when the PCM6 \cdot 2 is not mounted in the rack. |
| Real-Time Clock (RTC) battery | Real-time clock with replaceable coin-cell battery (replacement recommended every 5 years). CR2430 3V battery, rated for operation at -40 to 85 °C (-40 to 185 °F). This is not a standard CR2430 battery. The CR2430 battery is an available accessory. Contact DEIF for ordering. |
| Cooling | Passive |
| Temperature | CPU junction temperature measurement Software reset when the CPU temperature is too high |
| Operating system | GNU/Linux customized with PREEMPT real-time patch and system drivers C/C++ and CODESYS applications operate in user space mode Fail-safe remote SW update Power fail-safe, self-monitoring and error correcting file system (EXT-4) |
| System configuration | On-device, web-based configuration System information Host name configuration: The serial number is the default User access management: Operator, service, or administrator. Rights and credentials. Switch configuration: IPv4 address (static/dynamic) Fail-safe software update method (active / fall-back OS image) Simplified update procedures: No special tools, and the procedure is the same for OS and firmware Secure certificate-based access using standard protocols |
| System network protocols | Secure/SSH File Transfer Protocol (SFTP), server Secure Shell (SSH) TLS1.2 and TLS1.3 server and client Network Time Protocol (NTP), client Dynamic Host Configuration Protocol (DHCP), client EtherCAT master (native for C/C++ applications/system network scan) |
| PLC run-time | CODESYS V3 runtime : CODESYS V3 SP18 or later |
| Programming | IEC 61131-3: LD, SFC, FBD, CFC, ST (CODESYS V3.5 SP18+ IDE) ANSI C/C: + ANSI C/C using Linux SDK Python: As containerised software component |
| Visualisation | CODESYS web visualisation |
| Application protocols | See section Supported software features |
| Size | 50.80 mm (2 slots) |
| Weight | 241 g |
| Power consumption | Max 17.5 W, hereof 5.6 W W reserved for USB3.0 host |
| Connector, grip (included by default) | 2 x 12 terminals: DFMC 1.5/12-ST-3.5-LR – 1790580 |
| Connector, screw | 2 x 12 terminals: DFMC 1.5/12-STF-3.5 – 1790399 |

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LED specifications

| Run LED | | Description |
|--------------------|----|------------------|
| OFF | • | Initialisation |
| Green blinking | | Pre-operational |
| Single green blink | | Safe-operational |
| Green | • | Operational |
| Green flickering | ÷. | Boot loader |

| Status LED | | Description |
|------------|---|------------------|
| OFF | • | Off. |
| Green | • | Normal operation |

Ethernet

The CPU module can be used as a gateway between the network segments for plant-wide power management and the local network segments. To do this, two independent network interfaces must be made. Eth0 is an Ethernet port connected directly to the CPU, and Ethernet ports Eth1, Eth2, and Eth3 are connected to the CPU using a managed switch. The Eth0 port supports TSN on hardware level.

The module also supports PROFINET controllers (master) and PROFINET devices (slave) with CODESYS stacks.

CAN

The two independent CAN ports provide CAN (layer II) support. CANopen Master/Slave communication is done using the CODESYS protocol stacks. The ports are configured using the CODESYS applications. The applications also provide the CAN layer II and CANopen Master/Slave protocol stacks. Enable the termination resistors using the software, mapped to the Linux device interface.

UART

The two UART serial ports can be configured as RS-422 or RS-485. Enable the termination and bias resistors using the software, mapped to the Linux device interface.

DisplayPort

The DisplayPort connector standard for the graphical display port supports LED/LCD monitors. The standard is very robust in on-site operations in comparison to other commodity standards.

USB host

The USB host is needed to export data, log files, and so on. The host supports the connection of USB 3.0 mass storage devices. Use the Linux operating system to add support for other USB devices.

2.2.3 EtherCAT interface

The PCM6·1 and PCM6·2 modules have an EtherCAT connection to local I/O modules in the rack through the backplane. You can expand the EtherCAT network with the SIM6·2, SIM6·4, or SIM6·5, which allows you to connect to remote or distributed I/O racks. It is also possible to access the digital inputs and outputs in the PCM6·1 and PCM6·2 modules with the EtherCAT slave interface.

The digital output can be used as a CPU watchdog. If the EtherCAT network in your application is not controlled by the EtherCAT Master, then the watchdog function automatically opens the digital output after 100 ms. The watchdog function is applicable to all EtherCAT Slave modules. If the EtherCAT Master is not in operation, then the slave modules go to a default state (EtherCAT: SAFEOP). Digital outputs are set to LOW and analogue outputs are set to 0 mA or 0 V.

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2.3 Station interface modules

2.3.1 SIM6·1 module specifications

| Ethe | erCAT in | nterf | ace | |
|--------------|-------------------|------------|-------------------------|--|
| | | | Power supply | From backplane |
| п | SIM6·1 Run Port 1 | | Backplane interfaces | 1 x EtherCAT OUT (Port 3) - LVDS |
| ı | | | | 1 x EtherCAT IN (Port 0) Optical: 100BASE-FX, SC connectors, multimode fibre glass 50 μ m (OM2,OM3,OM4, 1310 nm) |
| ı | | | Interfaces | 1 x EtherCAT OUT (Port 1) Optical: 100BASE-FX, SC connectors, multimode fibre glass 50 µm (OM2,OM3,OM4, 1310 nm) |
| TOOT | | \bigcirc | Size | 25.40 mm |
| EtherCAT OUT | | | Weight | 83 g |
| ů | | | Power consumption | Typical 3.5 W (2 active fibre channels) |
| EtherCAT IN | Port 0 | ф ф | | |

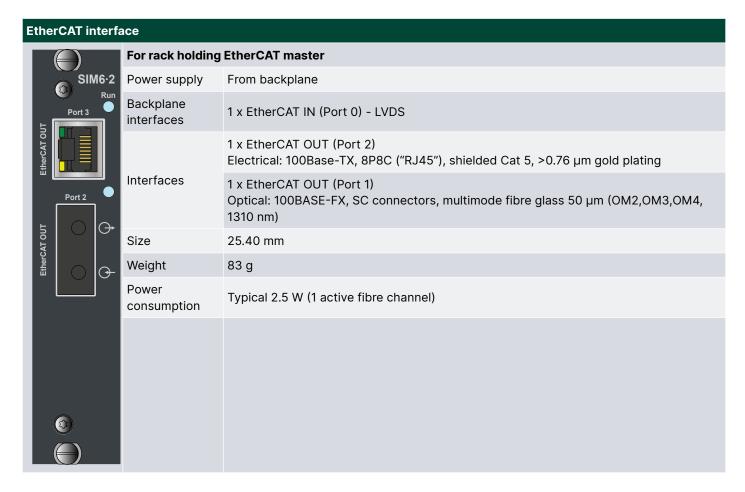
Terminal specifications

Configuration: Slave station

| Terminal | Description |
|--------------|-----------------------|
| EtherCAT IN | EtherCAT Logic Port 0 |
| EtherCAT OUT | EtherCAT Logic Port 1 |

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2.3.2 SIM6·2 module specifications



Terminal specifications

Configuration: Master station

| Terminal | Description |
|--------------|-----------------------|
| EtherCAT OUT | EtherCAT Logic Port 2 |
| EtherCAT OUT | EtherCAT Logic Port 1 |

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2.3.3 SIM6·3 module specifications

| EtherCAT interfa | ace | |
|------------------|----------------------|--|
| | Power supply | From backplane |
| SIM6·3 | Backplane interfaces | 1 x EtherCAT OUT (Port 3) - LVDS |
| Port 2 | | 1 x EtherCAT IN (Port 0) Electrical: 100Base-TX, 8P8C ("RJ45"), shielded Cat 5, >0.76 µm gold plating |
| Ether CAT OUT | Interfaces | 1 x EtherCAT OUT (Port 1) Optical: 100BASE-FX, SC connectors, multimode fibre glass 50 μm (OM2,OM3,OM4, 1310 nm) |
| тоо <u>г</u> (| | 1 x EtherCAT OUT (Port 2) Electrical: 100Base-TX, 8P8C ("RJ45"), shielded Cat 5, >0.76 µm gold plating |
| EtherCAT OUT | Size | 25.40 mm |
| | Weight | 83 g |
| Port 0 | Power consumption | Typical 2.5 W (1 active fibre channel) |
| EtherCAT IN | | |

Terminal specifications

Configuration: Slave station

| Terminal | Description |
|--------------|---|
| EtherCAT IN | EtherCAT Logic Port 0 |
| EtherCAT OUT | EtherCAT Logic Port 1 EtherCAT Logic Port 2 |

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2.3.4 SIM6·4 module specifications

Estimated release date: 2024. Contact DEIF for availability

The SIM6·4 module allows EtherCAT redundancy for the interconnection of multiple racks in a system via electrical connections. The Network Interface (NIC) is used for the EtherCAT master.

| EtherCAT interface | | | | |
|--------------------|----------------------------------|---|--|--|
| | For rack holding EtherCAT master | | | |
| SIM6·4 | Power supply | From backplane | | |
| Port 3 | Backplane interfaces | 1 x EtherCAT IN (Port 0) - LVDS | | |
| EtherCAT OUT | Interfaces | 1 x EtherCAT OUT (Port 3) Electrical: 100Base-TX, 8P8C ("RJ45"), shielded Cat 5, >0.76 µm gold plating | | |
| | | 1 x EtherCAT OUT (Port 1) Electrical: 100Base-TX, 8P8C ("RJ45"), shielded Cat 5, >0.76 µm gold plating | | |
| | Size | 25.40 mm | | |
| | Weight | 83 g | | |
| | Power consumption | Typical 2.5 W (TBC) | | |
| EtherCAT OUT | | | | |

Terminal specifications

Configuration: Master station

| Terminal | Description |
|--------------|-----------------------|
| EtherCAT OUT | EtherCAT Logic Port 3 |
| EtherCAT OUT | EtherCAT Logic Port 1 |

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2.3.5 SIM6·5 module specifications

Estimated release date: 2024. Contact DEIF for availability

The SIM6·5 module allows EtherCAT redundancy for the interconnection of multiple racks in a system via fibre optical connections. The Network Interface (NIC) is used for the EtherCAT master.

| Ethe | EtherCAT interface | | | | | | |
|--------------|--------------------|----------|----------------------------------|--|--|--|--|
| Г | | | For rack holding EtherCAT master | | | | |
| | SIM | | Power supply | From backplane | | | |
| п | | | Backplane interfaces | 1 x EtherCAT IN (Port 0) - LVDS | | | |
| ı | | | | 1 x EtherCAT OUT (Port 2) Optical: 100BASE-FX, SC connectors, multi-mode fibre glass 50 µm (OM2, OM3, OM4, 1310 nm) | | | |
| TOUT | Port 2 | • | Interfaces | 1 x EtherCAT OUT (Port 1) Optical: 100BASE-FX, SC connectors, multi-mode fibre glass 50 µm (OM2, OM3, OM4, 1310 nm) | | | |
| EtherCAT OUT | | _ | Size | 25.40 mm | | | |
| ш | | ⊕ | Weight | 83 g | | | |
| п | Port 1 | | Power consumption | Typical 3.5 W (2 active fibre channels) (TBC) | | | |
| EtherCAT OUT | | О | | | | | |

Terminal specifications

Configuration: Master station

| Terminal | Description |
|--------------|-----------------------|
| EtherCAT OUT | EtherCAT Logic Port 2 |
| EtherCAT OUT | EtherCAT Logic Port 1 |

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2.4 Power modules

2.4.1 PDM6·1 module specifications

| Power module | | | | | |
|--------------|---|---|--|--|--|
| PDM6·1 | Power supply | 30 W power supply Input level: 24 V (18 to 32 V) Black-out hold-up for 10 ms Polarity protection | | | |
| | Backplane power source | Power output to backplane | | | |
| 2 | Backplane interfaces | Not used | | | |
| | Size | 40.64 mm | | | |
| | Weight | 201 g | | | |
| | Power consumption | Standby typical 1.25 W | | | |
| | EMI filter | Common mode EMI input filter | | | |
| | Isolation | Input galvanic isolated from other potentials, 500 V DC | | | |
| DEIF | Connector, grip (included by default) | 2 terminals: 1792517 | | | |
| | Connector, screw | 2 terminals: 1873207 | | | |

LED specifications

| Power LED | | Description |
|-----------|--|--|
| Green | | The voltage is above the operating threshold and power is sourced from this input. |

Terminal specifications

| Terminal | | Description |
|----------|----------------|---------------------------------------|
| 1 | Power supply + | Power supply input, 24 V (18 to 32 V) |
| 2 | Power supply - | Power supply input, common |

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2.4.2 PDM6·2 module specifications

| Power module | | | | |
|-----------------------|---|--|--|--|
| PDM6·2 Power 1 Power | Power supply | 30 W power supply Input level: 24 V (18 to 32 V) Black out: 10 ms + 300 ms hold up time (~1 MB persistent storage on PCM6·1) Polarity protection | | |
| - 010 | Backplane power source | Power output to backplane | | |
| | Backplane interfaces | Not used | | |
| | Size | 40.64 mm | | |
| | Weight | 250 g | | |
| | Power consumption | Standby typical 1.25 W | | |
| | EMI filter | Common mode EMI input filter | | |
| | Isolation | Input galvanic isolated from other potentials, 500 V DC | | |
| DEIF | Connector, grip (included by default) | 2 terminals: 1792517 | | |
| | Connector, screw | 2 terminals: 1873207 | | |

LED specifications

| Power LED | | Description |
|-----------|---|--|
| Green | • | The voltage is above the operating threshold and power is sourced from this input. |

Terminal specifications

| Terminal | | Description |
|----------|----------------|---------------------------------------|
| 1 | Power supply + | Power supply input, 24 V (18 to 32 V) |
| 2 | Power supply - | Power supply input, common |

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2.5 Digital input and output modules

2.5.1 DIO6·1 module specifications

DIO6·1 is designed for the rough environment in a wind turbine, and all inputs and outputs are protected and isolated from other potentials.

| Digital input and output module | | | |
|---------------------------------|---|--|---|
| DIO6·1 | Power supply | From backplane Output from exte | ernal supply |
| Run 1 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | |
| 2 1001 17 18 | 10 digital | Supply | External supply 24V (12 to 32 V) |
| 4 1001 19 | outputs | Туре | Solid-state high side driver |
| 6 7007 21 | | Voltage | High > Supply voltage -1 V |
| | | Current | Max. 0.5 A per channel (UL: Max. 0.25 A per channel) Maximum total for all outputs: 2 A per group |
| 7 | | Response time | Max. 1 ms |
| 9 | | Isolation | 10 outputs in one group Isolated from other potentials, 500 V DC |
| 12 | | Protection | Short circuit protection Inverse supply voltage protection |
| | 16 digital inputs | Input | High: 13 to 30 V Low: -30 V to +5 V Reference to common |
| | | Load | Typically 6 mA (Vin >7 V) |
| | | Bandwidth | ~3 ms filter (200 Hz hardware low pass) |
| | | Isolation | 16 Inputs in 2 groups (8+8) Isolated from other potentials, 500 V DC |
| | Size | 25.40 mm | |
| | Weight | 91 g | |
| | Power consumption | Typical 0.75 W | |
| | Connector, grip (included by default) | 2 x 6 terminals: 1790522 2 x 9 terminals: 1790551 | |
| | Connector, screw | 2 x 6 terminals: 1 2 x 9 terminals: 1 | |

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2.5.2 DIO6-2 module specifications

DIO6.2 has 16 x digital inputs and 16 x digital outputs. All the inputs and outputs are protected and isolated from other potentials.

| Digital input and output module | | | | |
|--|---|--------------------------------------|---|--|
| | Power supply | From backplane | using PDM6·1 module or PDM6·2 module | |
| DIO6·2 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | | |
| 1 1001 21 | 16 digital outputs | Supply | External supply 24 V (12 to 32 V) | |
| 2 | | Туре | Solid-state high side driver | |
| 5 25 | | Voltage | High > Supply voltage -1 V | |
| 6 | | Current | Max. 0.5 A per channel Maximum total for all outputs: 2 A per group | |
| 10 10 30 | | Response time | Max. 1 ms | |
| 11 00 31 | | Isolation | 16 outputs in 2 groups (8+8) Isolated from other potentials, 500 V DC | |
| 12 TOOT 32 13 TOOT 33 14 TOOT 34 | | Protection | Short circuit protection with feedback signal from each group Inverse supply voltage protection | |
| 15 16 17 18 19 10 13 35 36 37 37 38 38 | 16 digital inputs | Input | High: 13 to 30 V Low: -30 V to +5 V Reference to common | |
| 20 1001 40 | | Load | Typically 6 mA (Vin >7 V) | |
| | | Bandwidth | ~3 ms filter (200 Hz hardware low pass) | |
| | | Isolation | 16 inputs in 2 groups (8+8) Isolated from other potentials, 500 V DC | |
| | Size | 25.40 mm | | |
| | Weight | 93 g | | |
| | Power consumption | Typical 0.75 W | | |
| | Connector, grip (included by default) | 2 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 | |
| | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 | |

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2.5.3 DIM6·1 module specifications

DIM6·1 has 32 x digital inputs. All the inputs are protected and isolated from other potentials.

| Digital input module | | | | | |
|-------------------------|---|---|---|--|--|
| | Power supply | From backplane | From backplane using PDM6·1 module or PDM6·2 module | | |
| DIM6·1 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | | | |
| 1 | 32 digital inputs | Input | High: 13 to 30 V Low: -30 V to +5 V Reference to common | | |
| 5 | | Load | Typically 6 mA (Vin >7 V) | | |
| 7 | | Bandwidth | ~3 ms filter (200 Hz hardware low pass) | | |
| 9 29 30 | | Isolation | 32 inputs in 4 groups (8+8+8+8) Isolated from other potentials, 500 V DC | | |
| | Size | 25.40 mm (1 slot |) | | |
| 11 | Weight | 89 g | | | |
| 13 33 34 14 15 35 16 36 | Power consumption | Typical 1.1 W | | | |
| 17 37 38 19 39 40 | Connector, grip (included by default) | 2 x 10 terminals: DFMC 1.5/10-ST-3.5-LR – 1790564 | | | |
| | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 | | |

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2.5.4 DOM6·1 module specifications

DOM6-1 has 32 x digital outputs. All the outputs are protected and isolated from other potentials.

| Digital output module | | | | |
|-----------------------|---|--------------------------------------|---|--|
| | Power supply | From backplane | using PDM6·1 module or PDM6·2 module | |
| DOM6·1 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | | |
| 1 1001 21 | 32 digital | Supply | External supply 24 V (12 to 32 V) | |
| 3 1001 23 | outputs | Туре | Solid-state high side driver | |
| 5 7 25 | | Voltage | High > Supply voltage -1 V | |
| 7 | | Current | Max. 0.5 A per channel Maximum total for all outputs: 2 A per group | |
| 10 10 30 | | Response time | Max. 1 ms | |
| 11 1001 31 | | Isolation | 32 outputs in 4 groups (8+8+8+8) Isolated from other potentials, 500 V DC | |
| 12 | | Protection | Short circuit protection with feedback signal from each group Inverse supply voltage protection | |
| 15 10 1 35 | Size | 25.40 mm | | |
| 17 | Weight | 97 g | | |
| 19 39 40 | Power consumption | Typical 0.5 W | | |
| | Connector, grip (included by default) | 2 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 | |
| | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 | |

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2.6 Analogue input and output modules

2.6.1 AIO6·1 module specifications

AlO6·1 is designed for the rough environment in a wind turbine, and all inputs and outputs are protected and isolated from other potentials.

| Analogue input | Analogue input and output module | | |
|-------------------------|---|---|---|
| | Power supply | From backplane | |
| AIO6·1 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | |
| 1 19 20 20 | 2 analogue outputs | Output type | Current mode: 0 to 20 mA, 4 to 20 mA Voltage mode: 0 to 10 V or -10 to 10 V. Software selectable. |
| 3 100 21 22 | | Output range | Current mode: 0 to 20 mA and 4 to 20 mA Voltage mode: 0 to 10 V and -10 to 10 V |
| 5 | | Load | Current mode: $< 500 \Omega$ Voltage mode: $\ge 1000 \Omega$ |
| 8 1001 26 | | Resolution | 16 bit |
| 10 28 | | Accuracy | 0.2 % of full range output (20 mA/10 V) at reference temperature 0.4 % of full range output (20 mA/10 V) at operational temperature |
| 11 29 12 30 13 31 | | Isolation | 2 outputs in one group Isolated from other potentials, 500 V DC |
| 14 | 16 analogue inputs | Input type | -10 to 10 V, 0 to 10 V, -20 to 20 mA, 0 to 20 mA and 4 to 20 mA. Software selectable. |
| 17 35 36 | | Impedance | Current mode: Max. 50 Ω Voltage mode: Min. 10 $k\Omega$ |
| | | Filter | 250 Hz hardware low-pass filter |
| | | Sampling | < 2 ms |
| | | Resolution | 16 bit |
| | | Accuracy | 0.2 % of full range input (20 mA/10 V) at reference temperature 0.4 % of full range input (20 mA/10 V) at operational temperature |
| | | Isolation | 16 inputs (8+8) in 2 groups Isolated from other potentials, 500 V DC |
| | Size | 25.40 mm | |
| | Weight | 96 g | |
| | Power consumption | Typical 2.75 W (2 analogue outsourcing 20 mA) | |
| | Connector, grip (included by default) | 2 x 2 terminals: 1 2 x 8 terminals: 1 | |
| | Connector, screw | 2 x 2 terminals: 1 2 x 8 terminals: 1 | |

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2.6.2 AIO6·2 module specifications

Scheduled release date: 2024. Contact DEIF for availability

AlO6·2 has 8 analogue inputs and 8 analogue outputs. The voltage and current modes for the inputs and outputs are individually software configurable. All the inputs and outputs are protected and isolated from other potentials.

| nalo | ogue input a | and output modul | | |
|-----------------------|---|---|--------------------------------------|--|
| (| | Power supply | · | using PDM6·1 module or PDM6·2 module |
| AIO6·2 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | (Port 0) - LVDS T (Port 1) – LVDS | |
| 1 2 3 4 5 | 1 21 22 22 3 4 5 1 0 1 25 | 8 analogue outputs | Output type | Current mode: 0 to 20 mA, 0 to 24 mA, 4 to 20 mA, and -20 to 20 mA Voltage mode: 0 to 10 V or -10 V to 10 V (20 % over-range option available on request) Software selectable. |
| 6 7 8 9 | 26 27 00 28 00 29 | | Output range | Current mode: 0 to 20 mA, 0 to 24 mA, 4 to 20 mA, and -24 to 24 mA Voltage mode: 0 to 10 V and -10 to 10 V |
| 0 | 30 | | Load | Current mode: $< 500 \Omega$ Voltage mode: $\geq 1000 \Omega$ |
| 1 | 1 00 31 | | Resolution | 16 bit |
| 2 3 4 | 32 33 34 | | Accuracy | 0.2 % of full range output (20 mA/10 V) at reference temperature 0.4 % of full range output (20 mA/10 V) at operational temperature |
| 5 6 7 | 35 36 37 | | Isolation | 8 outputs in 2 groups (4+4) Isolated from other potentials, 500 V DC |
| 18 19 20 | 39 40 | 8 analogue inputs | Input type | 0 to 10 V, -10 to 10 V, 0 to 20 mA, 4 to 20 mA, -20 to 20 mA. Software selectable. |
| | | | Impedance | Current mode: Max. 50 Ω Voltage mode: Min. 10 $k\Omega$ |
| (| | | Filter | 250 Hz hardware low-pass filter |
| | | | Sampling | < 2 ms |
| | | | Resolution | 16 bit |
| | | | Accuracy | 0.2 % of full range input (20 mA/10 V) at reference temperature 0.4 % of full range input (20 mA/10 V) at operational temperature |
| | | | Isolation | 8 inputs in 2 groups (4+4) Isolated from other potentials, 500 V DC |
| | | Size | 25.40 mm | |
| | | Weight | 118 g (incl. conne | ectors) |
| | Power consumption | Typical 5.25 W (8 analogue outsourcing 20 mA) (TBC) | | |
| | Connector, grip (included by default) | 2 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 | |
| | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 | |

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2.6.3 AOM6·2 module specifications

Scheduled release date: 2024. Contact DEIF for availability

AOM6·2 has 8 analogue outputs. The voltage and current modes for the outputs are individually software configurable. The outputs are protected and isolated from other potentials.

| logue outpu | t module | | | | |
|--|---|---|---|--|--|
| | Power supply | From backplane | using PDM6·1 module or PDM6·2 module | | |
| AOM6·2 | Backplane interfaces | | 1 x EtherCAT IN (Port 0) - LVDS 1 x EtherCAT OUT (Port 1) – LVDS | | |
| 11 12 12 13 14 15 15 | 8 analogue outputs | Output type | Current mode: 0 to 20 mA, 0 to 24 mA, 4 to 20 mA, - 24 to 24 mA Voltage mode: 0 to 10 V or -10 to 10 V (20 % over-range option available on request) Software selectable. | | |
| 16 17 17 18 19 | | Output range | Current mode: 0 to 20 mA, 0 to 24 mA, 4 to 20 mA and - 20 to 20 mA Voltage mode: 0 to 10 V and -10 to 10 V | | |
| 20 | | Load | Current mode: $< 500~\Omega$ Voltage mode: $\geq 1000~\Omega$ | | |
| | | Resolution | 16 bit | | |
| | | Accuracy | 0.2 % of full range output (20 mA/10 V) at reference temperature 0.4 % of full range output (20 mA/10 V) at operational temperature | | |
| | | Isolation | 8 outputs in 2 groups (4+4) Isolated from other potentials, 500 V DC | | |
| | Size | 25.40 mm | | | |
| | Weight | 100 g | | | |
| | Power consumption | Typical 4.75 W (8 analogue outsourcing 20 mA) (TBC) | | | |
| | Connector, grip (included by default) | 1 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 | | |
| | Connector, screw | 1 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 | | |

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2.6.4 AIM6·1 module specifications

Estimated release date: 2024. Contact DEIF for availability

AlM6·1 has 16 analogue inputs. The voltage and current modes for the inputs are individually software configurable. All the inputs are protected and isolated from other potentials.

| nal | logue input i | nodule | | |
|----------------------|----------------------------|---|---|---|
| | AIM6·1 | Power supply | From backplane | using PDM6·1 module or PDM6·2 module |
| | | Backplane interfaces | 1 x EtherCAT IN (Port 0) - LVDS 1 x EtherCAT OUT (Port 1) - LVDS | |
| 1 2 3 4 | 21 22 22 23 24 | 16 analogue inputs | Input type | 0 to 10 V , -10 to 10 V 0 to 20 mA, 4 to 20 mA, -20 to 20 mA Software selectable. |
| 5 6 7 | 25 26 27 27 | | Impedance | Current mode: Max. 50 Ω Voltage mode: Min. 10 $k\Omega$ |
| 9 | 28 29 | | Filter | 250 Hz hardware low-pass filter |
| 10 | 30 | | Sampling | < 2 ms |
| | | | Resolution | 16 bit |
| 11 12 13 14 | 31 32 33 33 | | Accuracy | 0.2 % of full range input (20 mA/10 V) at reference temperature 0.4 % of full range input (20 mA/10 V) at operational temperature |
| 15 16 17 | 35 36 37 | | Isolation | 16 inputs in 4 groups (4+4+4+4) Isolated from other potentials, 500 V DC |
| 18 19 | 38 39 | Size | 25.40 mm | |
| 20 | 40 | Weight | 100 g (TBC) | |
| | | Power consumption | Typical 5.25 W (TBC) | |
| | | Connector, grip (included by default) | 2 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 |
| | | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 |

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2.6.5 AIM6·2 module specifications

Estimated release date: 2024. Contact DEIF for availability

AlM6·2 has 8 analogue inputs. The voltage and current modes for the inputs are individually software configurable. All the inputs are protected and isolated from other potentials.

| alogue input | module | | |
|--------------|---|--------------------------------------|---|
| AIM6·2 | Power supply | From backplane | using PDM6·1 module or PDM6·2 module |
| | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | |
| 1 | 8 analogue inputs | Input type | 0 to 10 V, -10 to 10 V 0 to 20 mA, 4 to 20 mA, -20 to 20 mA Software selectable. |
| 5 | | Impedance | Current mode: Max. 50 Ω Voltage mode: Min. 10 $k\Omega$ |
| B | | Filter | 250 Hz hardware low-pass filter |
| 0 | | Sampling | < 2 ms |
| | | Resolution | 16 bit |
| | | Accuracy | 0.2 % of full range input (20 mA/10 V) at reference temperature 0.4 % of full range input (20 mA/10 V) at operational temperature |
| | | Isolation | 8 inputs in 2 groups (4+4) Isolated from other potentials, 500 V DC |
| | Size | 25.40 mm | |
| | Weight | 100 g (TBC) | |
| | Power consumption | Typical 5.25 W (TBC) | |
| | Connector, grip (included by default) | 2 x 10 terminals: | DFMC 1.5/10-ST-3.5-LR – 1790564 |
| | Connector, screw | 2 x 10 terminals: | DFMC 1.5/10-STF-3.5 – 1790373 |

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2.7 Temperature input modules

2.7.1 TIM6·1 module specifications

TIM6·1 is designed for the rough environment in a wind turbine, and all inputs and outputs are protected and isolated from other potentials.

| Temperature input module | | | | |
|----------------------------------|---|---|--|--|
| | Power supply | From backplane | | |
| TIM6·1 | Backplane interfaces | 1 x EtherCAT IN (Port 0) - LVDS 1 x EtherCAT OUT (Port 1) - LVDS | | |
| 1 1001 15 | 14 (6) | Sensor type | Pt100 | |
| 3 100 17 | temperature inputs | Range | -50 to 200 °C | |
| 5 TOT 19 6 TOT 20 7 TOT 21 | p. v. | Wire | 14 (2) x Pt 100 2-wire connection or 0 (6) x Pt 100 3-wire connection, selectable mix | |
| 8 1001 22 | | Sampling | ≤ 100 ms | |
| | | Cable error | Open input and short-circuit are detected | |
| 9 1001 23 | | Resolution | 0.1 °C (16 bit ADC) | |
| 10 | | Accuracy | 1.0 °C at reference temperature2.5 °C at operational temperature(2-wire cables must be shorter than 1 m) | |
| 14 28 | | Isolation | 14 (6) inputs in one group Isolated from other potentials, 500 V DC | |
| | Size | 25.40 mm | | |
| | Weight | 90 g | | |
| | Power consumption | Typical 1.0 W (all inputs connected) | | |
| | Connector, grip (included by default) | 2 x 8 terminals: 1790548 2 x 6 terminals: 1790522 | | |
| | Connector, screw | 2 x 8 terminals: 1 2 x 6 terminals: 1 | | |

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2.8 Communication interface modules

2.8.1 IFM6·1 module specifications

IFM6·1 is designed for the rough environment in a wind turbine, and all inputs and outputs are protected and isolated from other potentials.

The interface and Fieldbus module offer 2 x Profibus DP master and 2 x RS-485 ports.

| Con | Communication interface module | | | | |
|--------|--------------------------------|---|--------------------------------------|---|--|
| Г | | Power supply | From backplane | | |
| ı | IFM6·1 | Backplane interfaces | 1 x EtherCAT IN (1 x EtherCAT OU | | |
| 1 | | Processor | 196 MHz industri | al grade 32 bit microcontroller | |
| | 10 | 2 x Profibus DP Master | Supported baud rates | 9600, 19200, 45450, 93750, 187500, 500000, 1.5M, 3.0M, 6.0M, 12.0M < 1% error | |
| 3 4 | 11 12 12 | | Biasing and termination | On or off (software select) | |
| п | | | Standards | PROFIBUS DP-V0 (cyclic data and diagnostics) | |
| | | | Slaves | Max. 5 per Profibus DP Master | |
| 5 6 | 13 14 14 | Com 2 x | Standards | TIA/EIA-485 shielded twisted copper cable | |
| П | | RS-485 interfaces | Baud rate | 2400, 4800, 9600, 19200, 38400, 45450, 57600, 115200, 230400 and 460800 < 1 % error | |
| 7 | 15 15 | | Word length | 7 or 8 bits | |
| 8 | 16 | | Parity | None, even, odd | |
| п | | | Stop bits | 1 or 2 | |
| п | | | Flow control | None | |
| ı | | | Communication lines | 2 wire half duplex | |
| | | | Biasing and termination | On or off (software selected) | |
| | | Isolation | Each communica | tion port isolated from other potentials, 500 V DC | |
| | | Size | 25.40 mm | | |
| | | Weight | 90 g | | |
| | | Power consumption | Typical 3.25 W (4 ports active) | | |
| | | Connector, grip (included by default) | 2 x 2 terminals: 1 | 790483 | |
| | | Connector, screw | 2 x 2 terminals: 1 | 790292 | |

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2.8.2 IFM6·2 module specifications

IFM6 \cdot 2 is designed for the rough environment in a wind turbine, and communication ports are protected and isolated from other potentials. The IFM6 \cdot 2 interface and Fieldbus module offer CAN, 2 x SSI and 2 x High speed counter input.

| Com | munication | interface module | | | |
|----------|---------------|---|--|---|--|
| | | Power supply | From backplane | | |
| 1 2 | 1 15 15 16 | Power supply, SSI | Input level: 24 V (18 to 32 V) Note 1: SSI power input must be left unconnected if SSI is unused. Note 2: SSI power input has a TVS (Transient Voltage Suppression) diode of 33V to shield to protect the connected SSI encoder from damage during surge and burst test Therefore, the SSI interface is not galvanic isolated from shield. | | |
| 3 | 17 18 | Backplane interfaces | | 1 x EtherCAT IN (Port 0) - LVDS 1 x EtherCAT OUT (Port 1) - LVDS | |
| | | Processor | 240 MHz industrial grade 32 bit microcontroller | | |
| 5 6 | 19 20 | CAN interfaces | Standards | ISO 11898 | |
| 7 | 100 21 | | Baud rate | 20, 50, 100, 125, 250, 500, 800 or 1000 kbit/s Sample point at 70 to 85 % < 1% error | |
| 9 | 22 1001 23 | | Isolation | Isolated from other potentials, 500 V DC | |
| 10 | 24 | | Termination | Open/120 Ω (software select) | |
| 11 | 25 | | Protection | 24 V DC resistant data lines | |
| 12 13 | 26 27 27 | 2 x SSI | Standards | TIA/EIA-422 shielded twisted copper cable | |
| 14 | 28 | | Bit rate | 250 kbps and 1000 kbps | |
| | | | Word length | 16 - 32 bit (default 25 bit). Binary or Gray-code configurable in SW | |
| | | | Termination | Fixed | |
| _ | | | Communication lines | 4 wire (clock and data) | |
| | | | Protection | 24 V DC resistant data lines | |
| | | | Isolation | Isolated from other potentials, 500 V DC | |
| | | | Isolation, SSI | SSI power input has a TVS diode of 33V to shield to protect the connected SSI encoder from damage during surge and burst test. Therefore, the SSI interface is not galvanic isolated from shield. | |
| | | 2 x digital input with frequency | Input | High: 13 to 30 V Low: -30 V to +5 V | |
| | | measurement | Load | Typically 6mA (Vin >7V) | |
| | | | Bandwith | 125 kHz hardware low-pass filter | |
| | | | Isolation | Isolated from other potentials, 500 V DC | |
| | | Size | 25.40 mm | | |
| | | Weight | 92 g | | |
| | | Power consumption | Typical 3.0W | | |
| | | Connector, grip (included by default) | 2 x 2 terminals: 1 2 x 4 terminals: 1 | | |
| | | Connector, screw | 2 x 2 terminals: 1 2 x 4 terminals: 1 | | |

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2.9 Condition monitoring modules

2.9.1 CMM6·x module specifications

Contact DEIF for availability

The module has built-in current excitation and all inputs are optically isolated from other potentials. CMM6·1 and CMM6·2 provide up to 4 high frequency analogue inputs. Use the inputs for:

- Measuring voltage signals up to 20 kHz
- Interfacing IEPE vibration sensors

CMM6·1 specifications

| ONINO 1 Specifications | | | | |
|--|--|--|--|--|
| 2 x high frequency analogue input module | | | | |
| | Power supply | From backplane | | |
| CMM6·1 | Backplane interfaces * | 1 x EtherCAT® OUT (Port 0) – LVDS 1 x EtherCAT® OUT (Port 1) – LVDS | | |
| | | Sensor type | IEPE or Voltage input | |
| 2 1001 6 | | Excitation | Current: Selectable 0, 2, 4 and 6 mA Voltage: 24 V (minimum) | |
| | | Input range | Selectable range: DC-mode: -10 to 20, ±10 to ±5, 2.5, 1.25, 0.62, 0.31, 0.16, 0.08, 0.40, 0.20 V (11 steps) IEPE (AC)-mode: ±10, 5, 2.5, 1.25, 0.62, 0.31, 0.16, 0.08, 0.40, 0.20 V (10 steps) | |
| | | Impedance | 300 kOhm | |
| 3 11001 7 | 2 High frequency analogue inputs | Frequency range | DC- mode: 0.05 to 20.000 Hz (3dB) Anti-aliasing filter (DC/AC mode): Low pass -3 dB, 20 kHz butterworth, 3rd order, 77 dB in stop band @ >30 kHz AC- mode (IEPE): High pass is 0.05 Hz | |
| | | Sample rate | Up to 57kHz, 2 channels simultaneous Software selectable sample rate : 57594, 29297,14648 or 7324 Hz Selectable down sampling : 1:2, 1:5, 10, 25, 50, 100, 250, 500, 1000, 2500, 5000 | |
| | | Resolution | 24 bit delta-sigma $\Delta\Sigma$ (including sign) 300 nV (gain 1, Range $\pm 2,5$ Vp) ENOB = 19 @ OSR=256, 29297 sps | |
| | | SNR | Typical > 100 dB @ Range ±2.5 Vp | |
| | | Accuracy | ± 0.5 % of selected range | |
| | | Diagnostic | Wire-break and short circuit | |
| | | Isolation | 2 inputs in 2 groups, each optically isolated from other potentials, 500 V DC | |
| | Connector, grip | CMM6·1: 2 x 2 terminals: 1790483 (included by default) | | |
| | Size | 25.4 mm | | |
| | Weight | 110 g | | |
| | Power consumption | Max. 4 W | | |

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CMM6·2 specifications

4 x high frequency analogue input module Power supply From backplane 1 x EtherCAT® OUT (Port 0) - LVDS CMM6·2 Backplane 1 x EtherCAT® OUT (Port 1) - LVDS interfaces * Sensor type IEPE or Voltage input Current: Selectable 0, 2, 4 and 6 mA Excitation Voltage: 24 V (minimum) Selectable range: • DC-mode: -10 to 20, ±10 to ±5, 2.5, 1.25, 0.62, 0.31, 0.16, 0.08, Input range 0.40, 0.20 V (11 steps) AC- mode (IEPE):±10, 5, 2.5, 1.25, 0.62, 0.31, 0.16, 0.08, 0.40, 0.20 V (10 steps) Impedance 300 kOhm DC- mode: 0.05 to 20.000 Hz (3dB)Anti-aliasing filter Frequency DC/AC mode: Low pass -3 dB, 20 kHz butterworth, 3rd order, 77 dB range in stop band @ >30 kHz 4 High IEPE (AC)-mode: High pass is 0.05 Hz frequency Up to 57kHz, 4 channels simultaneous (Max 20kHz via EtherCAT for analogue inputs 4 channels) Sample rate Software selectable sample rate: 57594, 29297,14648 or 7324 Hz Selectable down sampling: 1:2, 1:5, 10, 25, 50, 100, 250, 500, 1000, 2500, 5000 24 bit delta-sigma $\Delta\Sigma$ (including sign) Resolution 300 nV (gain 1, Range ±2,5Vp) ENOB = 19 @ OSR=256, 29297 sps **SNR** Typical > 100 dB @ Range ±2.5 Vp Accuracy ± 0.5 % of selected range Diagnostic Wire-break and short circuit 4 inputs in 4 groups, each optically isolated from other potentials, Isolation 500 V DC Connector, grip CMM6·2: 2 x 2 terminals: 1790483 (included by default) Size 25.4 mm Weight 110 g Power Max. 6 W consumption

* Data is buffered and transferred continuously via EtherCAT® to the EtherCAT® master. Use of data transfer bandwidth on the EtherCAT® bus has to be considered. The number of high speed analogue channels, down sampling rate and collecting intervals, and CPU power of EtherCAT® master has influence on bandwidth used for data transfer.

Available on request:

- Sample CODESYS application and library for Basic Signal processing, Frequency Analysis, Statistics, Level detection for Warning and Alarms.
- CMM6·3 and CMM6·4: 2- and 4-channel variants with shielded M12 connectors.

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2.10 Accessories

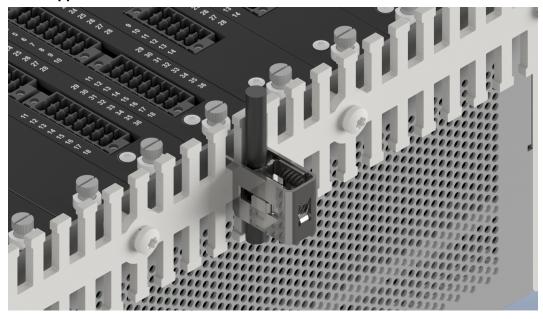
2.10.1 Wire support

The controller rack can be ordered with wire support brackets that are pre-mounted from the factory. The wire support is a 3 x 10 mm metal bar with hooks to secure and support wires, and is mounted at the top and bottom of the rack.

Shield clamps, typically used for communication cables (3 to 10 mm in diameter), can be mounted on the wire support bar. The clamps provide an EMC shield that is close to the input terminals.

| Rack | Accessory |
|----------|-----------------------|
| Rack6·10 | Wiresupport, Rack6·10 |
| Rack6·12 | Wiresupport, Rack6·12 |
| Rack6·14 | Wiresupport, Rack6·14 |
| Rack6·4 | Wiresupport, Rack6·4 |
| Rack6·6 | Wiresupport, Rack6·6 |
| Rack6·8 | Wiresupport, Rack6·8 |

Wire support bracket mounted on a controller rack



2.10.2 Optional connector kits

| Connector kit | Description |
|------------------|--------------------------|
| Conn. kit AlO6·1 | Connector kit for AIO6·1 |
| Conn. kit CMM6·1 | Connector kit for CMM6·1 |
| Conn. kit CMM6·2 | Connector kit for CMM6·2 |
| Conn. kit DIO6·1 | Connector kit for DIO6-1 |
| Conn. kit IFM6·1 | Connector kit for IFM6-1 |
| Conn. kit IFM6·2 | Connector kit for IFM6-2 |
| Conn. kit PCM6·1 | Connector kit for PCM6·1 |
| Conn. kit PCM6·2 | Connector kit for PCM6·2 |

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| Connector kit | Description |
|------------------|---|
| Conn. kit PDM6·1 | Connector kit for PDM6·1 |
| Conn. kit PDM6·2 | Connector kit for PDM6·2 |
| Conn. kit TIM6·1 | Connector kit for TIM6·1 |
| Conn. kit 120 | Connector kit for I/O module (1 pcs 2 x 20 pin) |
| Conn. kit 140 | Connector kit for I/O module (2 pcs 2 x 20 pin) |

2.10.3 Modules

Blank

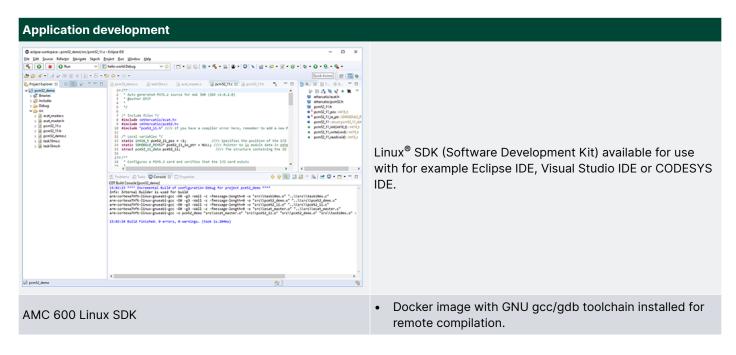
| Specifications | |
|----------------|----------|
| Size | 25.40 mm |
| Weight | 25 g |

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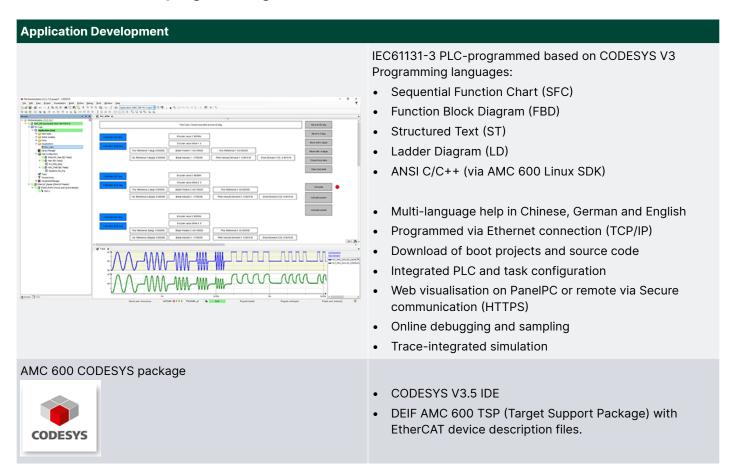
3. Application development

3.1 Software packages

3.1.1 C/C++ programming



3.1.2 IEC61131-3 programming



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3.1.3 Supported software features

| Software | AMC 600 Linux SDK | AMC 600 CODESYS (with Web visualization) | |
|------------------------|---|---|--|
| PLC runtime | - | CODESYS V3.5 SP18+ | |
| Programming | | | |
| IEC61131-3 | - | LD, SFC, FBD, CFC, ST | |
| | - | CODESYS V3.5 SP18+ IDE | |
| C/C++ | ANSI C/C++ | Yes, as External Implemented libraries components and Components (.so files) | |
| Network protocols | | | |
| | File Transfer Protocol (FTP), server and client (disabled by default) | | |
| | Secure/SSH File Transfer Protocol (SFTP), server | | |
| | Trivial File Transfer Protocol (TFTP), client | | |
| | Secure Copy (SCP), server and client | | |
| | Secure Shell (SSH), version 2, server and client | | |
| | Network Time Protocol (NTP), client | | |
| | Dynamic Host Configuration Protocol (DHCP), client | | |
| | Access to cUrl from Linux OS | | |
| Visualisation | | | |
| | HTML5/Javascript via build-in webservers | CODESYS Web visualisation | |
| System Configuration | | | |
| | Webbased system configuration for IP address (static/dynamic), host name, change root, operator, admin, service user passwords, system information etc. | | |
| Device handling | See separate Application Note https://docs.deif.com/secure/linux-sdk- examples/interface-local-io-pcm61- via-ethercat-vscode/index.html | CODESYS Device handling (EtherCAT Master, CANOpen Manager, Profibus Master etc.) | |
| Configuration | | | |
| Visualisation designer | | CODESYS V3.5 visualisation | |
| Scope/trace | | Scope/trace | |
| HMI visualisation tool | | CODESYS web visualisation | |
| | | Panel PC and remote HMI client (communication via HTTPS) Requires: Browser with HTML5/JavaScript support, such as Chrome, Firefox, Safari, Edge, and more | |
| Controller redundancy | - | Yes - CODESYS Controller Redundancy (Option) | |

Communication protocols

| The state of the s | | | | |
|--|-------------------|---|--|--|
| Software | AMC 600 Linux SDK | AMC 600 CODESYS (with Web visualization) | | |
| OPC UA Server | - | Yes - CODESYS OPC UA Server | | |
| OPC UA Client | - | Yes - CODESYS OPC UA Client via Single License (purchase separately from CODESYS Store) | | |
| Modbus TCP Server | - | Yes - Modbus TCP Server (CODESYS) | | |

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| Software | AMC 600 Linux SDK | AMC 600 CODESYS (with Web visualization) |
|--|-------------------|--|
| | | libModbus (DEIF) |
| Modbus TCP Client | - | Yes - Modbus TCP Server (CODESYS) libModbus (DEIF) |
| Modbus RTU Master | - | Yes - Modbus TCP Server (CODESYS) libModbus (DEIF) |
| Modbus RTU Slave | - | Yes - Modbus RTU Slave (CODESYS) |
| EtherCAT Master | Yes | Yes - EtherCAT Master (CODESYS) |
| CAN Layer II | - | Yes - via CODESYS library |
| CANopen Master | - | Yes - CANopen Master (CODESYS) |
| CANopen Slave | - | Yes - CANopen Slave (CODESYS) |
| PROFINET V2.3 Class A RT CONTROLLER | - | Yes - (CODESYS) |
| PROFINET V2.3 Class A RT DEVICE | - | Yes - (CODESYS) |
| Others | | On request or via CODESYS Single License |

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4. Legal information

4.1 Disclaimer and copyright

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